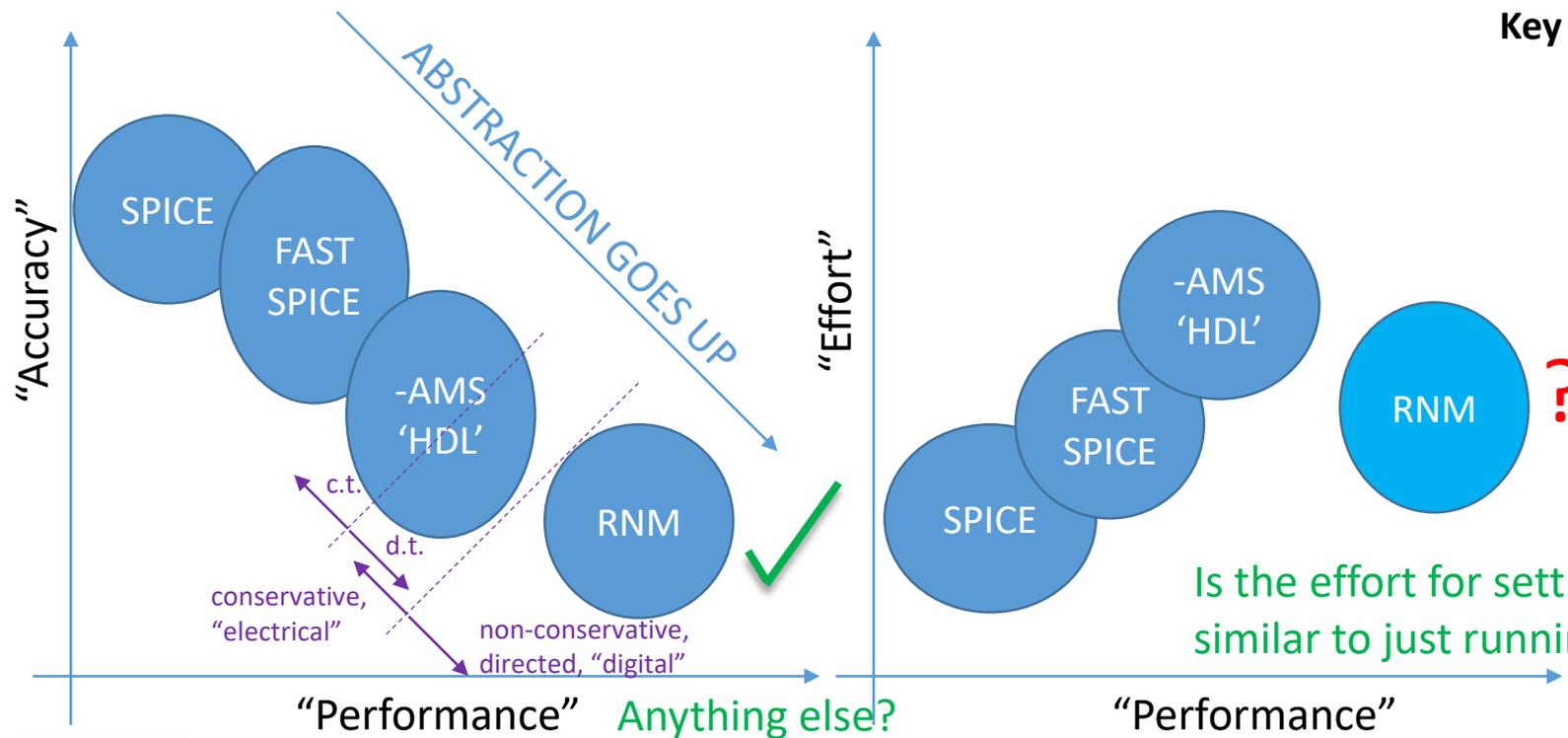


Beyond real number modeling: Comparison of analog modeling approaches.

Wolfgang Scherr, FDL 2020, 17th Sep, Kiel

A qualitative view on state of the art:

- Behavioral modeling of M/S systems



Are these really (and always) advantages?

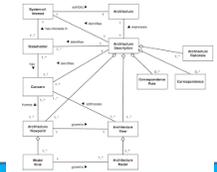
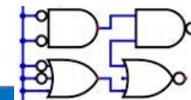
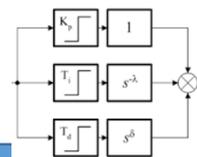
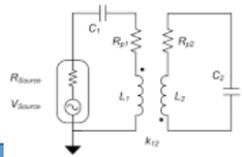
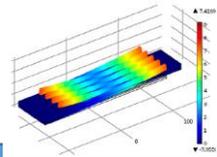
Key advantages of RNM:

- Discrete solver only
- Very high simulation performance ?
- Event driven or sampled data modeling of analog operation
- No analog solver, no convergence problems!
- Can be written by analog designers and/or digital verification engineers

Is the effort for setting up RNM models similar to just running a (fast) SPICE simulation?



Models, models, everywhere...



Finite Element	Nonlinear Conservative	Linear Conservative	Linear Non-Conservative	Dataflow	Discrete Event	Transactions, Threads, ...	Algorithmic/ Meta / SW
HFSS, ADS, Momentum, ... <i>(Keysight, Ansys, ...)</i>	Simulink/Plecs				<i>(Mathworks or Simetrix Suite)</i>		Matlab
	(Open)Modelica (incl. multiphysics)						Ptolemy/...
	(H)Spice				VHDL	Digital Simulators	Excel/VBA, etc.
	VHDL-AMS				Verilog		ISO C/C++
	Verilog-A				SystemVerilog		SysML/UML /XML/...
	Analog Simulators				SystemC	incl. TLM	Python (NumPy)
							Octave

time continuous

time discrete

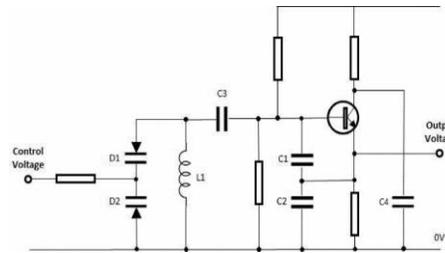
(often) timeless (by order, etc...)



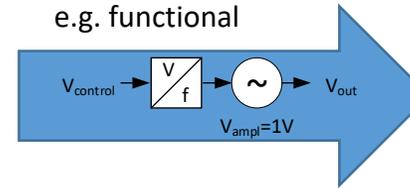
Please note: qualitative, not exhaustive and simplified overview. There are many, many more tools and languages out there, these are just representing some most common ones!

What about the effort?

- VCO example^{*)}



implicit assumption of abstract behaviour e.g. functional

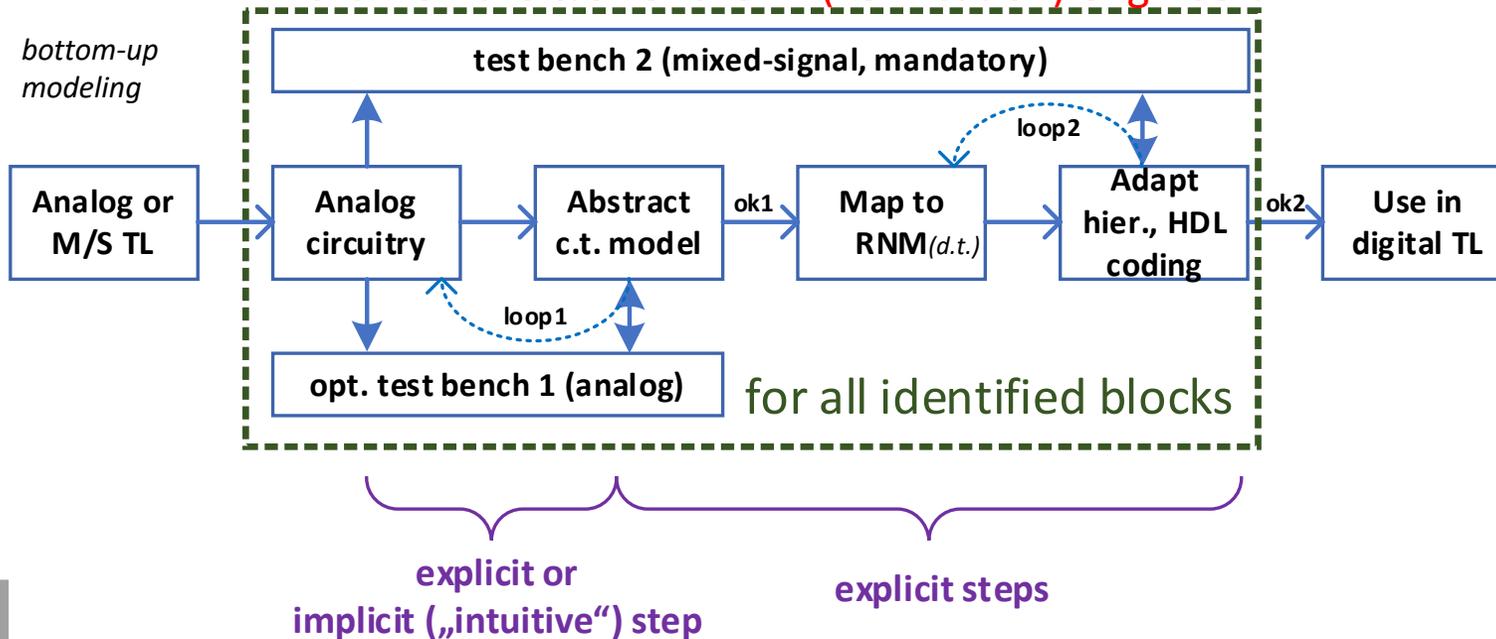


```

parameter real min_volt = 0.62913907284;
parameter real max_volt = 1.58940397351;
parameter real min_freq = 0.95 * ghz, max_freq = 3.4 * ghz;
parameter real amp = 1.0;
...
assign kvco = (max_freq-min_freq) * 2;
always @(Vcont)
  fcont = (Vcont-min_volt) / kvco;
always @(Vcont)
  begin
    if (Vcont < min_volt)
      freq_out = min_freq;
    else if (Vcont > max_volt)
      freq_out = max_freq;
    else
      freq_out = min_freq + fcont * kvco;
  end
...
multiplied_clk = multiplied_clk;
sine_wave_gen = sine_wave_gen(multiplied_clk, .data_out(data_out));
DAC2 dac2(.data_out, .out(sine_wave_system_clk));
assign Yout = amp * sine_wave_system_clk;
    
```

How to match model with design?

This is NOT the task of the TL (verification) engineer!



Important facts:

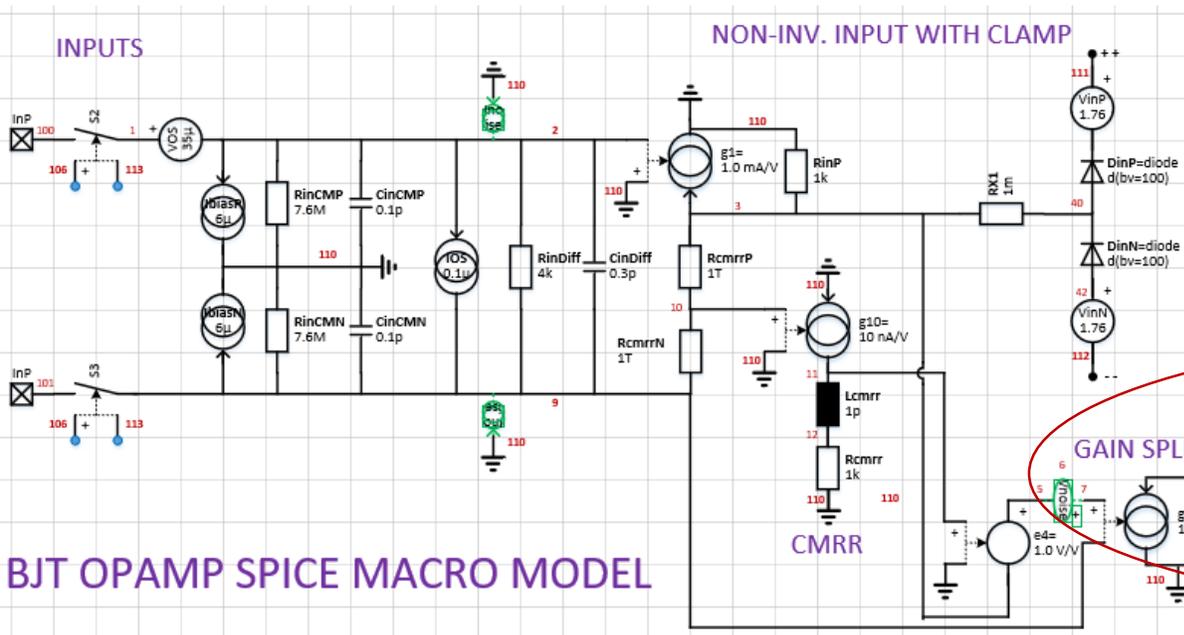
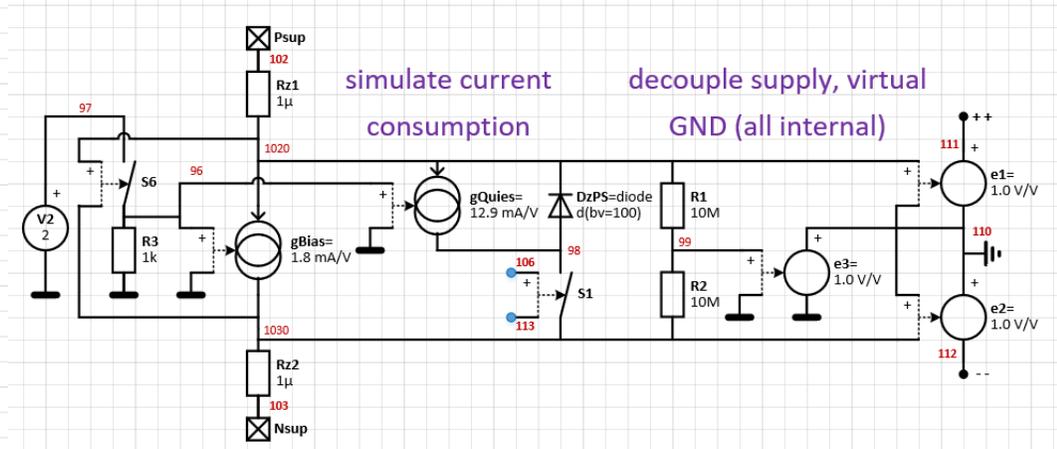
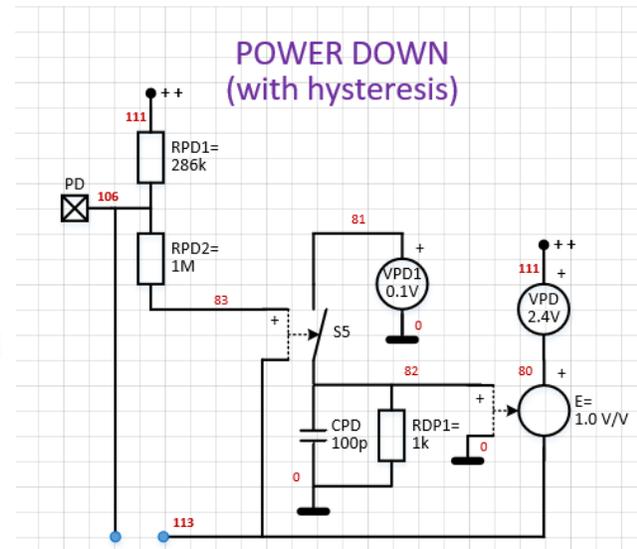
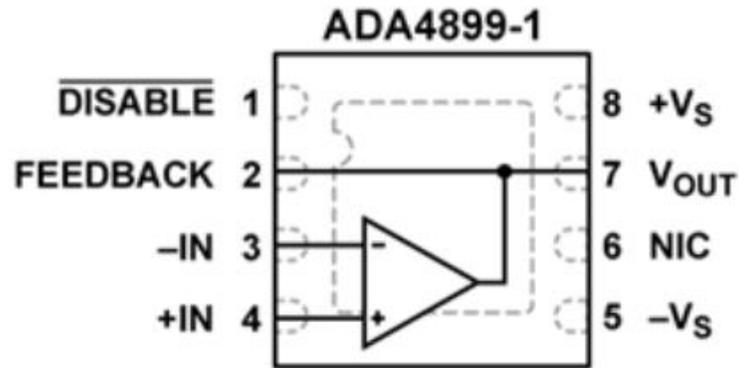
Additional tasks/effort/skills on top of analog design!

- .) the engineer is **trained and skilled** for writing **efficient, stable** HDL models
- .) writing **maintainable models** which can be re-used or updated on design changes
- .) implicit or (well documented) explicit analog abstraction of (SPICE) circuits
- .) the model itself has a **proper verification coverage** to safely replace the circuit

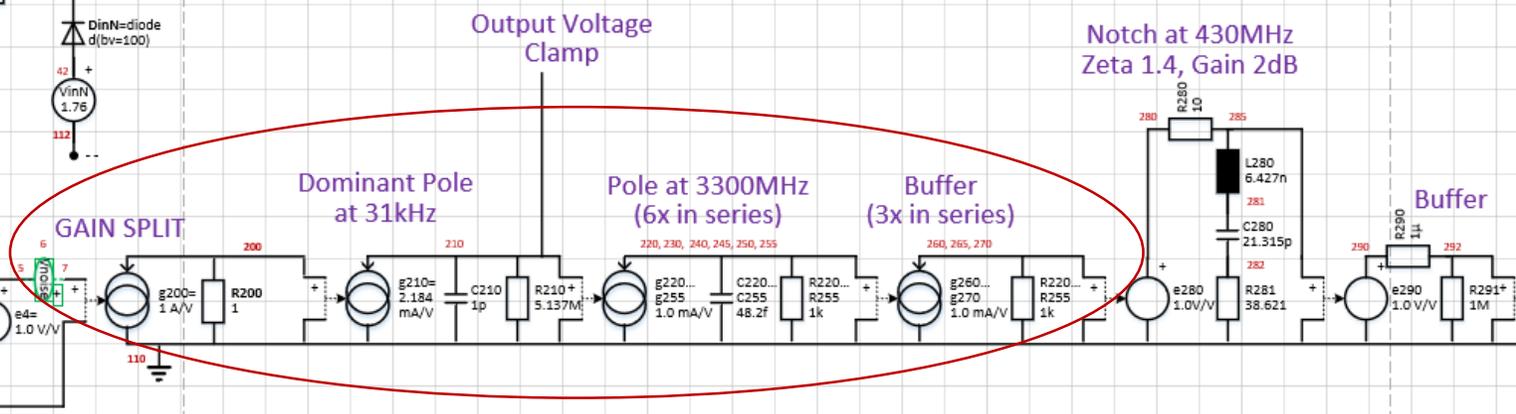
^{*)} Source: "Design of a SystemVerilog-Based VCO Real Number Model", N. Georgouloupoulos et al, MOCAS 2019

Many functional aspects in real-live (complex) circuits...

Source: Analog Devices
Datasheet and LT-Spice model

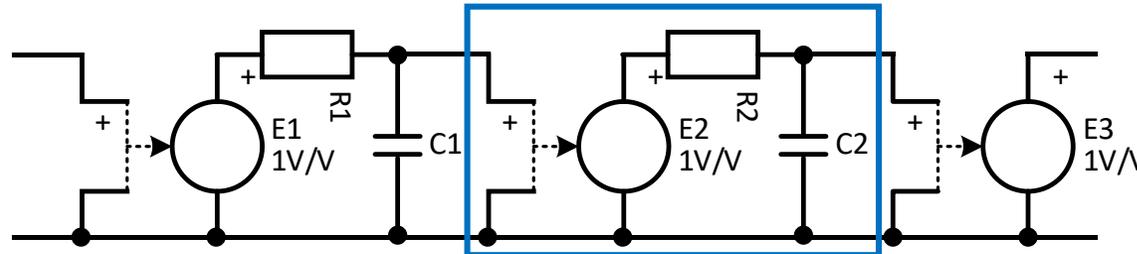


Assuming most important behavior: gain and lowpass characteristics.



BJT OPAMP SPICE MACRO MODEL

RNM using SystemVerilog and SystemC



```

`timescale 1ns/1ps
// RC lowpass model using an IIR representation
// (based on classic ct -> dt transformation)
// (c) 2020 Carinthia University of Applied Science
module RC_LP(input vreal inp, output vreal outp);
  parameter real R=1e3; // series resistance [Ohm]
  parameter real C=1e-9; // capacitance [F]
  parameter real fs=1e6; // sample frequency [Hz]
  // initial calculations
  real Ts = 1.0 / fs;
  import "DPI" pure function real exp (input real x);
  real a = exp(-Ts/(R*C));
  // internal storage node
  real z_int = 0.0;
  // filter function in z domain
  always #(Ts*1s) begin
    z_int = a*z_int + (1.0 - a)*inp;
  end
  assign outp = z_int;
endmodule

```

SV

```

// sc ports
sc_core::sc_in<double> inp;
sc_core::sc_out<double> outp;
// parameters
const struct params
{
  double R; /** resistor value [Ohm] */
  double C; /** capacitor value [F] */
  double fs; /** sample rate [s] */
  params() { R = 1e3; C = 1e-9; fs = 1e6; }
} p;
// states
struct lp_de_coded::states
{
  float z_int;
  states(const params& p) { z_int = 0.0; }
};

// SC_THREAD filter_process
void lp_de_coded::filter_process()
{ static double Ts = 1.0/p.fs;
  static double a = exp(-Ts/(p.R*p.C));
  while(true) {
    s.z_int = a*s.z_int + (1.0-a)*inp.read();
    outp.write(s.z_int);
    wait(Ts, SC_SEC);
  }
}

```

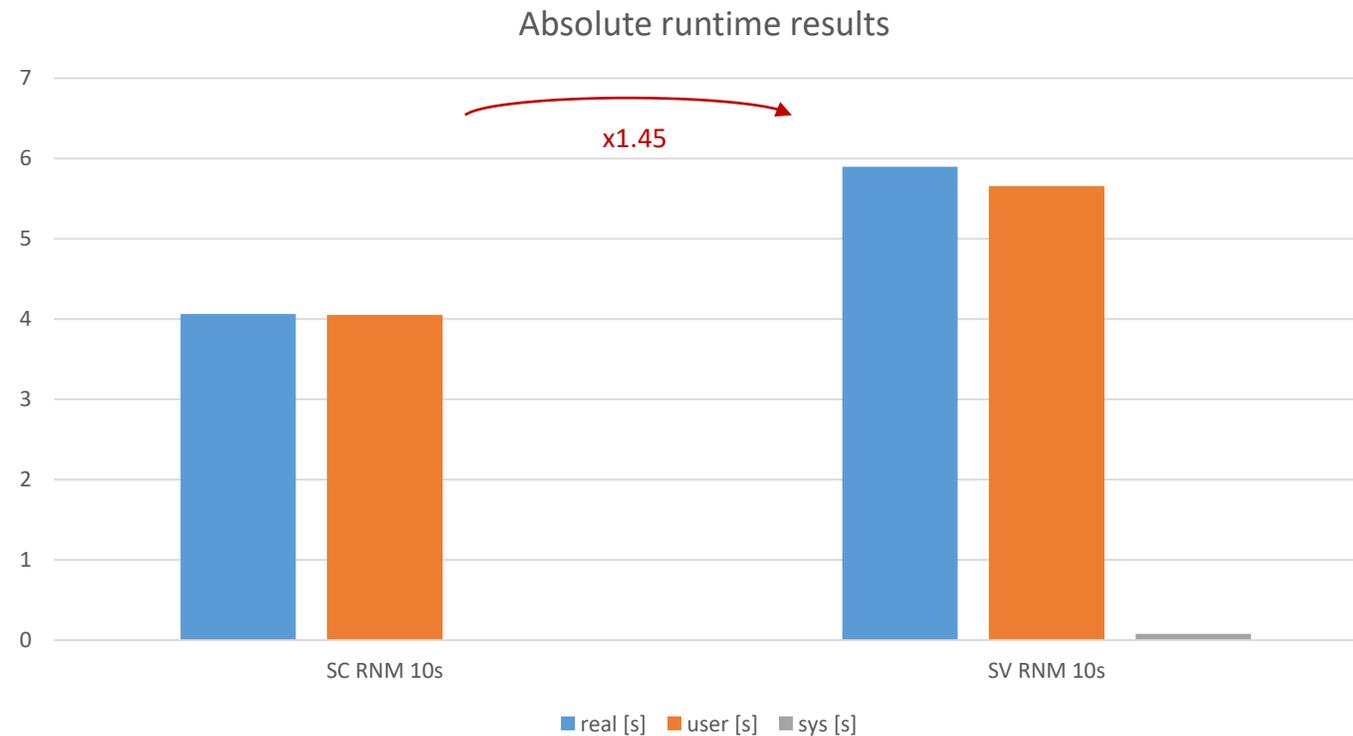
SC

RNM implement „mini-simulators“
 running their MoC in each instance –
 hard to have global control e.g. of
 speed versus precision...



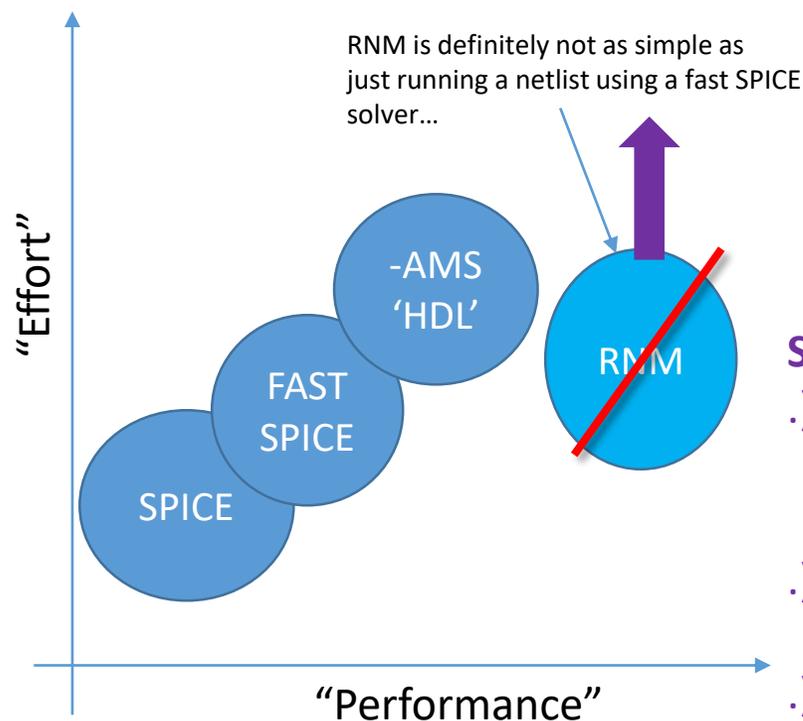
But these “mini-simulators” can be fast: RNM performance of SysC and SV

- RNM models execute in about half the real-time speed...



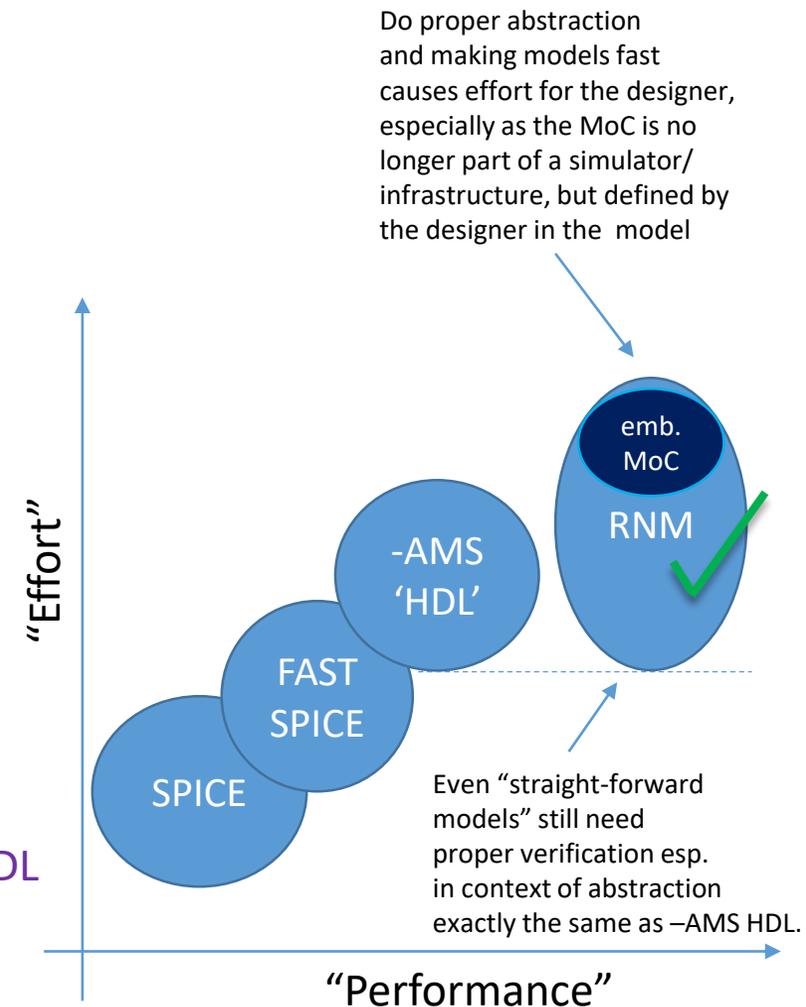
A qualitative view on “state of the art”

- Revising the effort diagram on RNM modeling



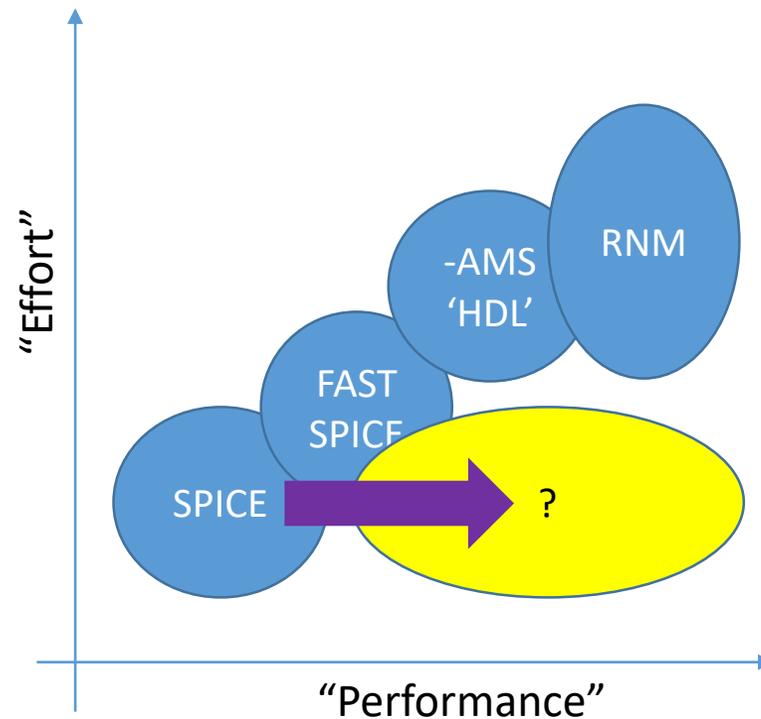
Simulation performance is not “for free”:

- .) effort to set up (proper abstraction, explicit/implicit model definition) *if not done top-down from system/concept level*
- .) experience to write efficient models in a HDL *additional skill for an analog designer*
- .) good verification and knowledge of model limitations within its context is important *additional skill for an analog verification engineer*

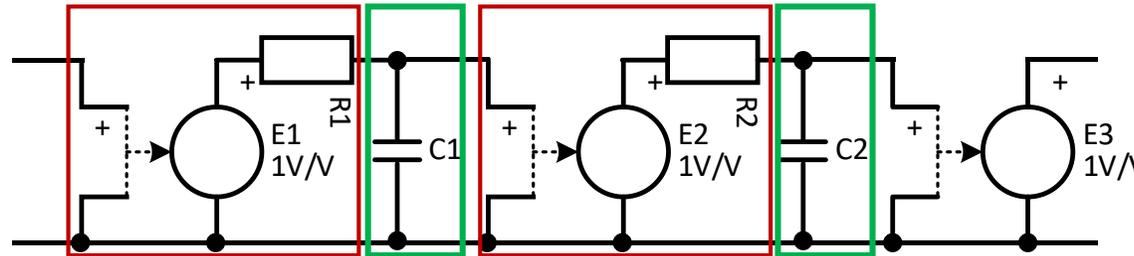


Beyond “state of the art” of RNM...

- Can we stick to a “more SPICE like level” **keeping modelling efforts low**, but still improve performance similar (or close to) to RNM?



The EEnet approach in SystemVerilog



```

`timescale 1ns/1ps
import EE_pkg::*;

// EEnet voltage controlled voltage source model ("to ground")
// Carinthia University of Applied Science

module EE_E(Pi,Po);
  inout EEnet Pi;          // positive control input
  inout EEnet Po;         // positive source output

  parameter real gain=1.0; // voltage gain [V/V]
  parameter real rout=1.0; // output resistance [Ohm]
  parameter real fs=1e6;  // sampling frequency [Hertz]

  // internal variables
  real Ts=1/fs;           // integration (=sample) time
  real Vnew=0.0;          // new output voltage

  // update for each sample timepoint
  always #(Ts*1s) begin
    Vnew = gain*Pi.V;
  end

  // update EEnet node
  assign Po = '{Vnew,0,rout};

endmodule

```

```

`timescale 1ns/1ps
import EE_pkg::*;

// EEnet capacitor model ("to ground")
// (c) 2020 Carinthia University of Applied Science

module EE_C(P);
  inout EEnet P;
  parameter real C=1e-9; // capacitance [F]
  parameter real fs=1e6; // sampling frequency [Hz]

  // internal variables
  real Ts=1/fs;           // integration (=sample) time
  real Ic=0;              // charge current
  real Vnet=0,Rnet=Ts/C; // set values to EEnet
  real Vlast=0;           // store last node voltage

  // update for each sample timepoint
  always #(Ts*1s) begin
    // new integration step
    Ic = (Vlast-Vnet)/Rnet;
    Vnet = P.V + Ic*Rnet;
    // remember node voltage
    Vlast = P.V;
  end

  // update EEnet node
  assign P = '{Vnet,0,Rnet};

endmodule

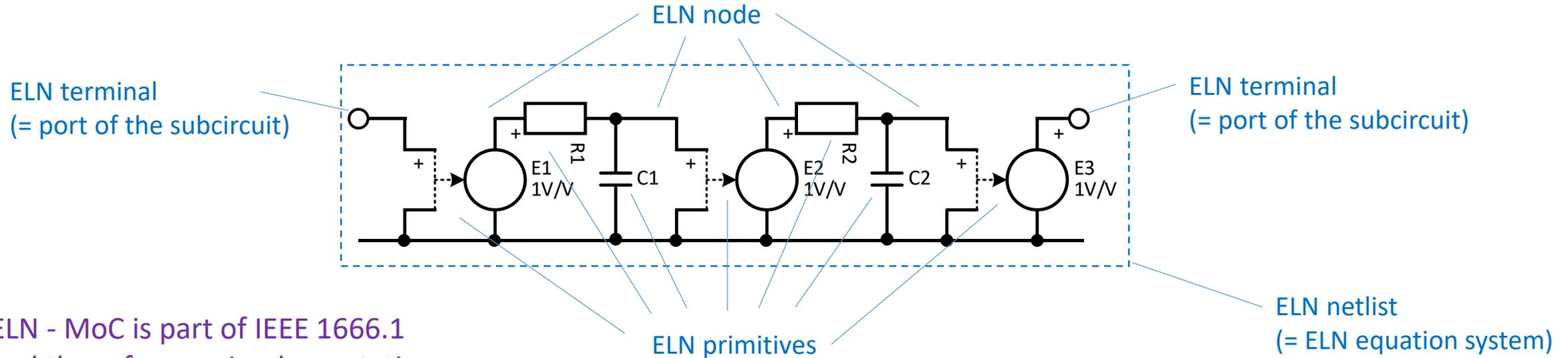
```

Be aware:

- .) still an abstraction (or kind of translation) step to re-partition the SPICE model is needed as well as a c.t. -> d.t. transform (similar RNM).
- .) MoC is still (partially) in the hand of the designer.
- .) separating the series-R requires to implement an iterative solver in the model → **inefficient!**



SystemC-AMS enables again simple schematics entry + netlisting...



ELN - MoC is part of IEEE 1666.1 and the reference implementation.
 → designer focuses on the model again!

Table 4.1—ELN primitive modules *)

ELN module name	Description
sca_eln::sca_r	Resistor
sca_eln::sca_c	Capacitor
sca_eln::sca_l	Inductor
sca_eln::sca_vcvs	Voltage controlled voltage source

...and many more

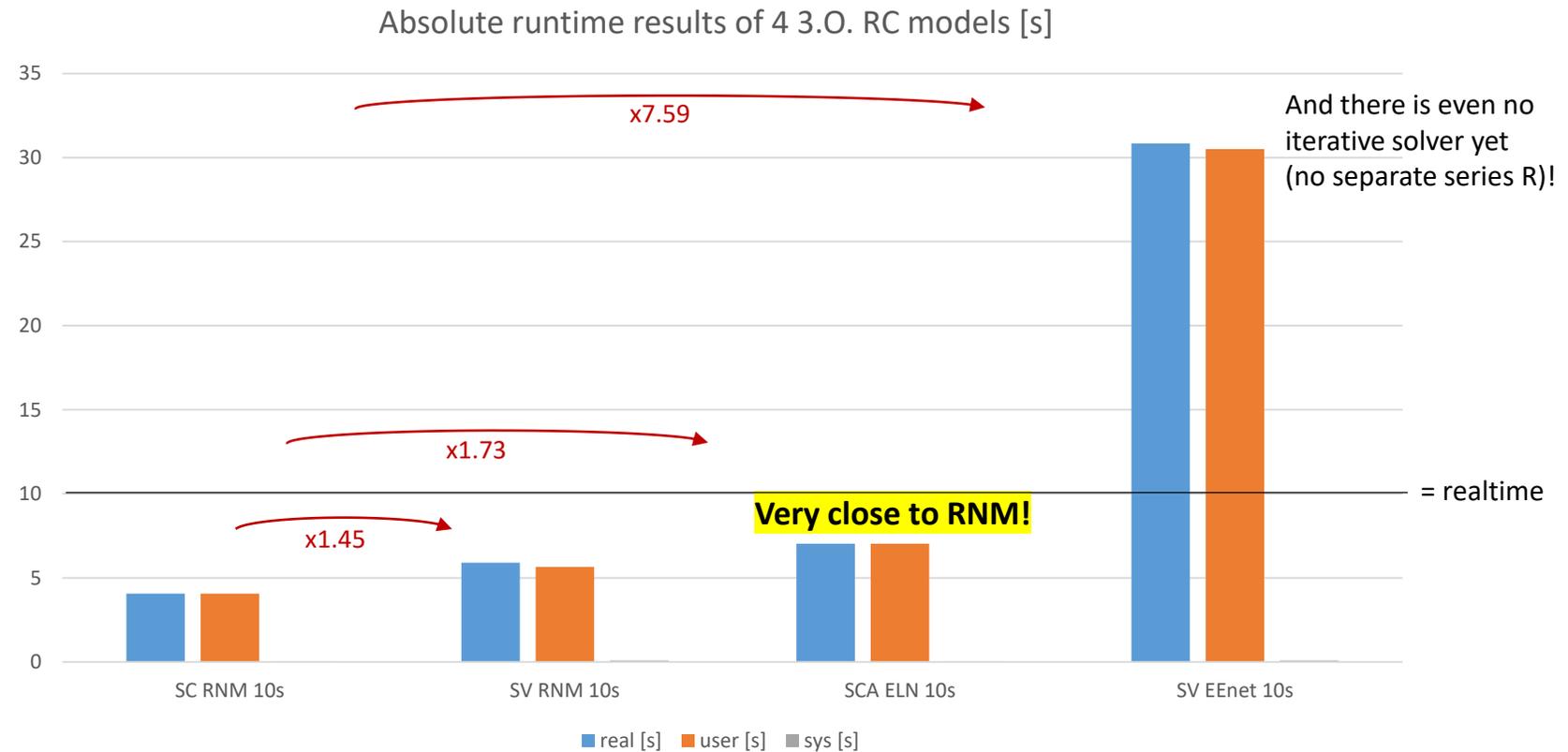
**But SPICE is slow!
 And now you tell us to use something like SPICE ?!?!?!?**



*) Source: "SystemC Analog/Mixed-Signal User's Guide User Perspective on IEEE Std. 1666.1-2016", Jan. 2020
https://www.accellera.org/images/downloads/standards/systemc/Accellera_SystemC_AMS_Users_Guide_January_2020.pdf

What about performance ?

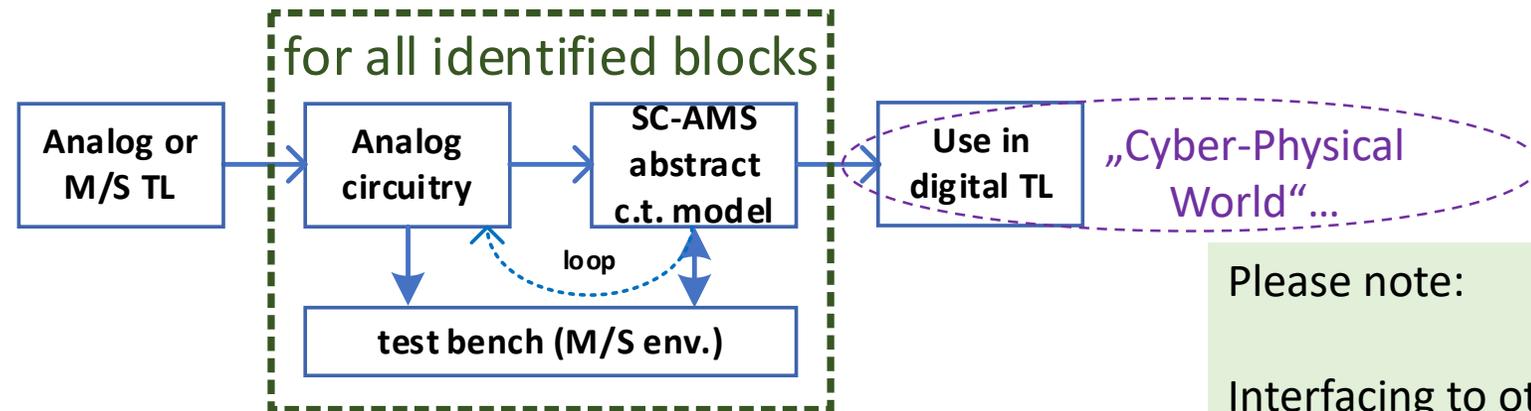
- SystemC-AMS easily outperforms SystemVerilog EEnet



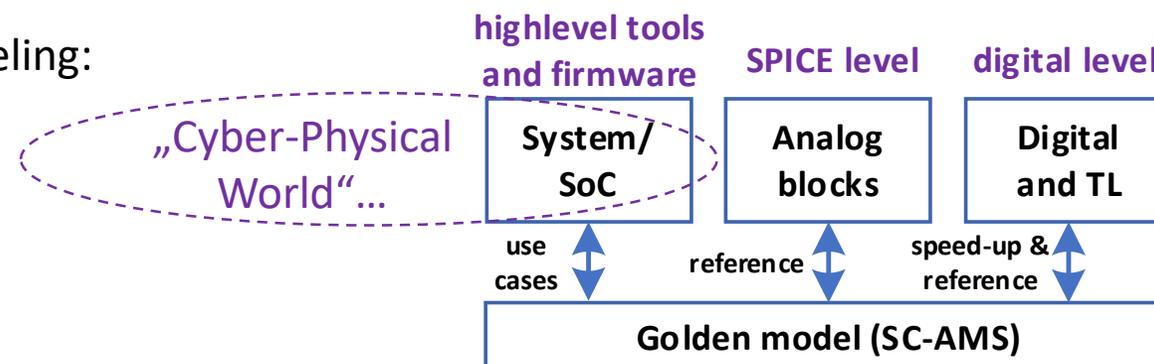
SystemC-AMS allows analog designers to do what they can do best...

- Simplified analog modeling flow:

„Bottom up“ modeling designs:



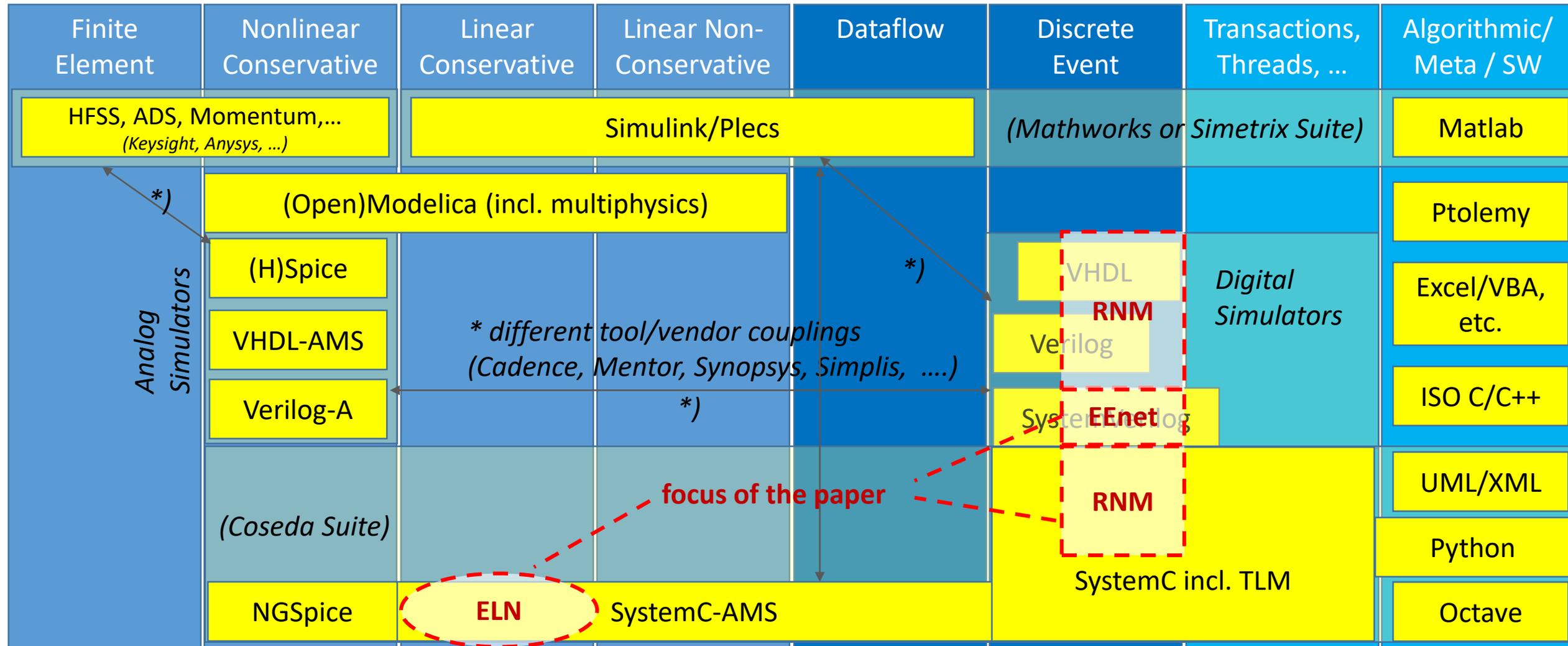
„Top-down“ modeling:



Might be nice to have FMI etc. for standardized interfaces...?



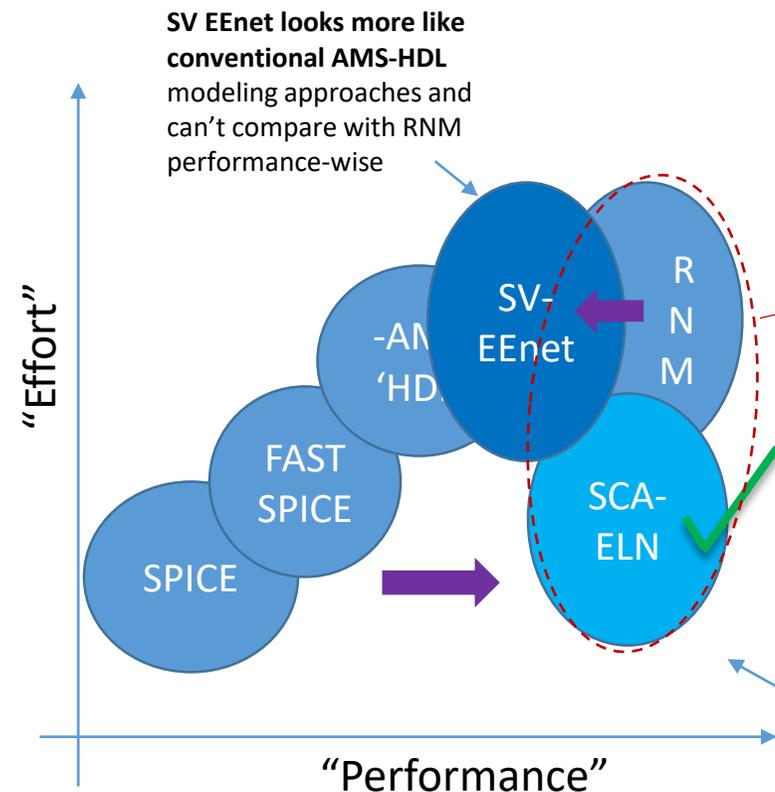
Conclusion I: SystemC-AMS bridges gaps



Please note: qualitative, not exhaustive and simplified overview. There are many, many more tools and languages out there, these are just representing some most common ones!

Conclusion II: effort and performance

- SystemC-AMS can improve analog modeling significantly
→ in terms of effort and performance !



Please note:

IEEE 1666 / 1666.1 allows to use (SC-)RNM together with SCA-ELN and other standard MoCs to find a **good balance between performance, abstraction, modelling effort** (e.g. also nonlinear behavior).

SCA-ELN provides the possibility to directly re-use (linear) SPICE models in a fast, digital environment close to RNM performance, given a stable reference implementation these models created from SPICE could be even **“correct by construction”**... (But I always advice to verify the models!)

